

Yuda Fan

<https://kurodakanbei.github.io/>

Preferred Interview Language: C++

Email : mistergalahad@gmail.com

Mobile : +41-76-475-0337

EDUCATION

- **ETH Zürich** Zürich, Switzerland
Master of Science in Computer Science; Direct Doctorate Program Sep. 2021 - Jun. 2024 (Expected)
- **Shanghai Jiao Tong University** Shanghai, China
Bachelor of Engineering in Computer Science; GPA: 3.92/4.30, 90.3/100 Sep. 2016 - Jun. 2020

EXPERIENCE

- **CADMO, ETH Zürich** Zürich, Switzerland
Researcher in Prof. Emo Welzl's Group Oct 2022 - Present
 - **Unique Sink Orientation:** Study the combinatorial structure of all the USOs of the same cube, and characterize the symmetric difference map between any ordinary USO and the uniform USO. Figure out all the affine transformations under which the USO polytope is a fixed point.
 - **Hidden Points and Hidden Vertices:** Prove that the hidden point problem is in $\exists\mathbb{R}$, and the VC-dimension of visible area set system is bounded by the logarithm of the number of reflex vertices. Introduce novel techniques such as convex/reflex chains and continuous visibility graph, and find solutions for spiral polygons, funnel polygons, pseudo-triangles, fan-shaped polygons, and staircase polygons. *Master's Thesis*
 - **Skills: Graph Theory, Computational Complexity, Computational Geometry, Scientific Writing**
- **Meituan** Beijing, China
Machine Learning Engineer in AI Center Jul. 2020 - Feb. 2021
 - **AutoVision:** A cloud platform to automatically conduct neural architecture search, model compression and hyperparameters optimization based on the MNN framework.
 - **Memory-Efficient Neural Architecture Search:** A training and inference scheme to eliminate the performance collapse in memory-efficient NAS. *Highest level core patent in 2020*
 - **Skills: Machine Learning, Pytorch, iOS APP Dev, Swift**
- **MVIG, Shanghai Jiao Tong University** Shanghai, China
Undergraduate Researcher in Prof. Cewu Lu's Group Jul. 2018 - Jun. 2020
 - **CyberPanda:** A novel universal robotic arm simulator with photorealistic visual feedback; Integrate the remote procedure call system, rendering pipeline and the physics engine in the platform. *Bachelor's Thesis*
 - **Transferable Active Grasping:** Improve the viewpoint optimization strategy to deal handle sparse reward issue, resulting in a reliable grasping algorithm with higher success rate. *ICRA 2020*
 - **Skills: Computer Vision, Deep Learning, Unreal Engine 4, C#, gRPC**

SELECTED AWARDS

- **Outstanding Graduate of Shanghai Jiao Tong University** Jun. 2020
- **The First Prize Scholarship at Shanghai Jiao Tong University** 2016-2018
- **2nd Place, ICPC 2021-2022 Swiss Subregional Individual Contest** Nov. 2021
- **2nd Place, ACM-ICPC 2017-2018 Hua-Lien Regional Contest** Nov. 2017
- **Gold Medal 6th Place, ACM-ICPC 2017-2018 Xi'an Regional Contest** Oct. 2017

SELECTED PUBLICATIONS

- Xiaoxing Wang*, Xiangxiang Chu*, **Yuda Fan**, Zhexi Zhang, Junchi Yan, *ROME: Robustifying Memory-Efficient NAS via Topology Disentanglement and Gradients Accumulation, ICCV 2023*
- Xiangyu Chen*, Zelin Ye*, Jiankai Sun, **Yuda Fan**, Fang Hu, Chenxi Wang, and Cewu Lu, *Transferable Active Grasping and Real Embodied Dataset, ICRA 2020.*